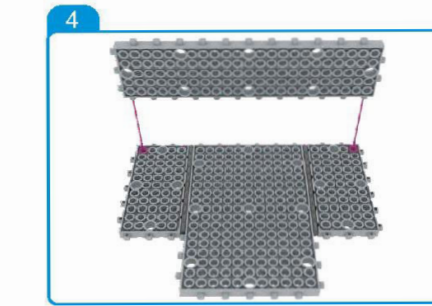
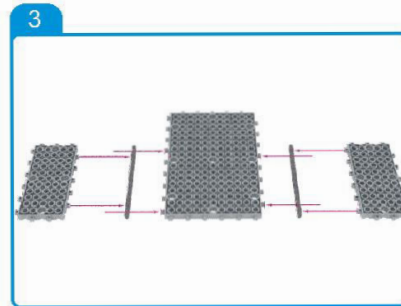
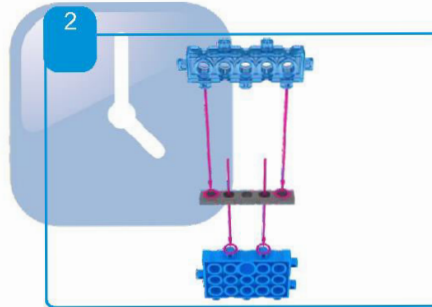
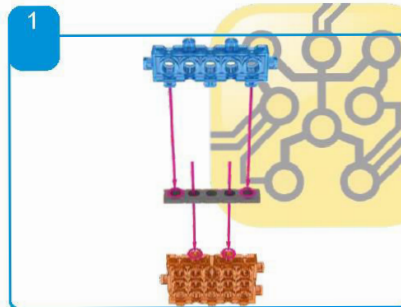




## Gear Left Gear Right



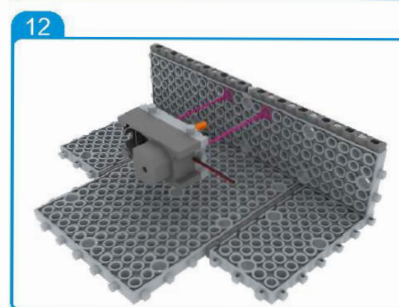
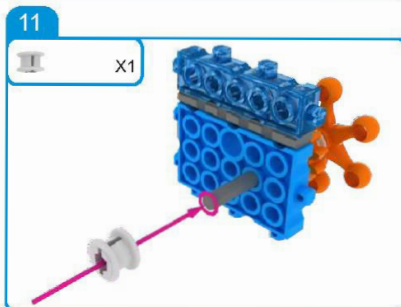
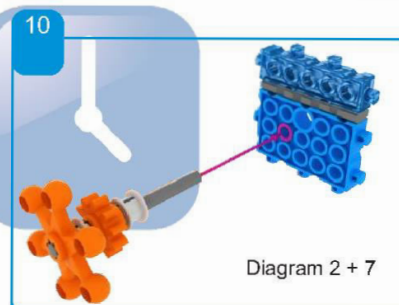
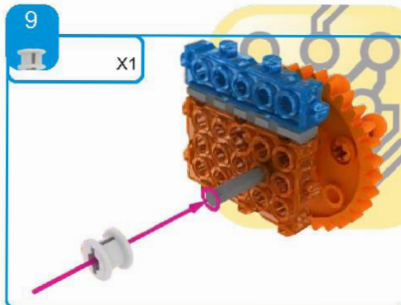
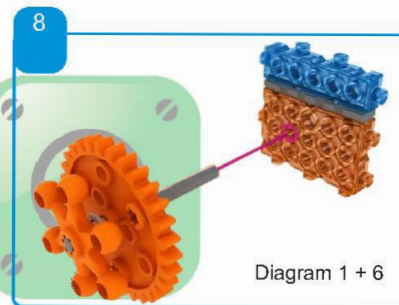
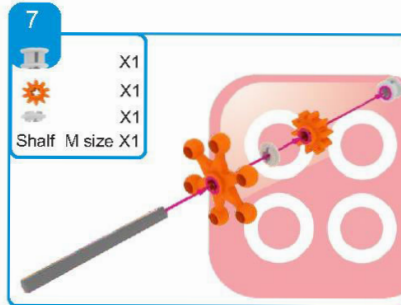
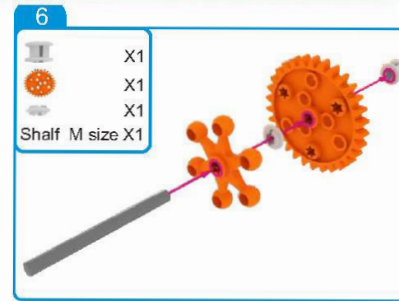
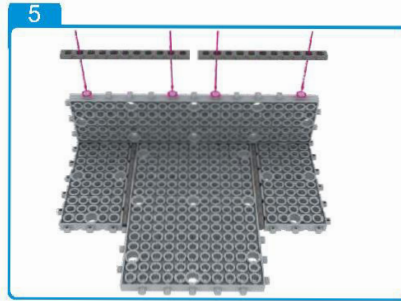
Gear teeth are designed to ensure the pitch circles of engaging gears roll on each other without slipping, providing a smooth transmission of rotation from one gear to the next



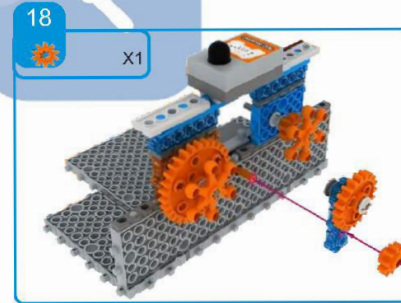
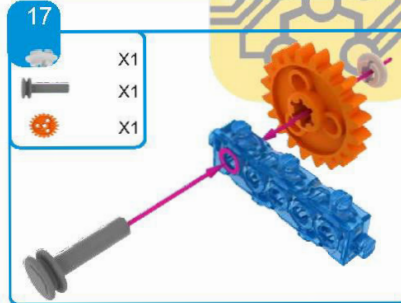
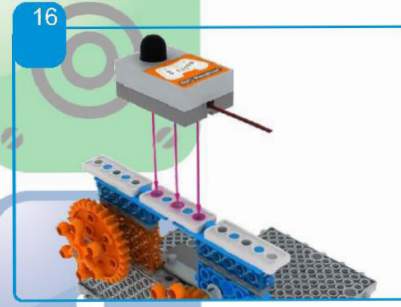
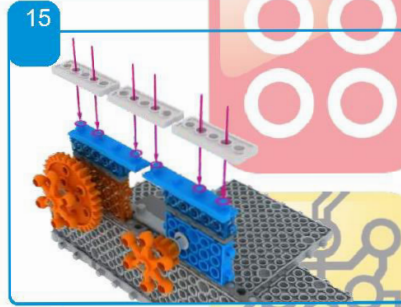
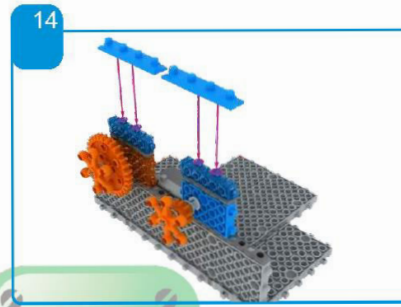
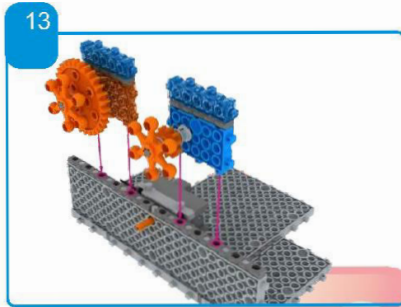
S SIZE

M SIZE

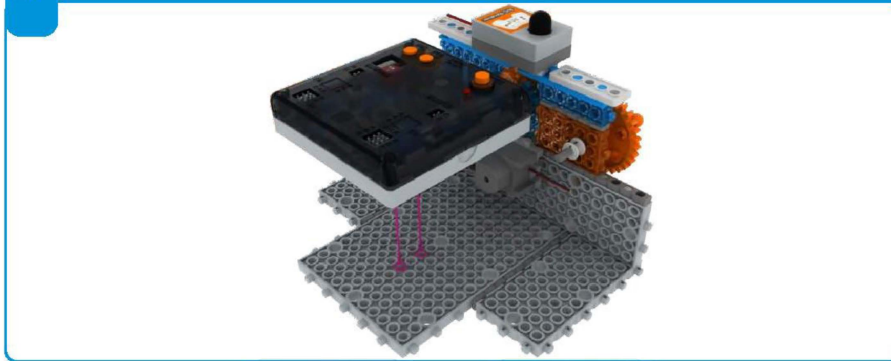
L SIZE



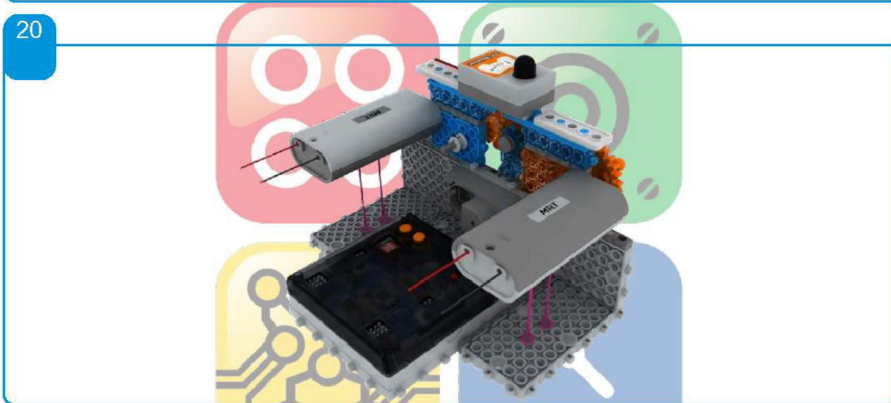
S SIZE      M SIZE      L SIZE



19



20



End



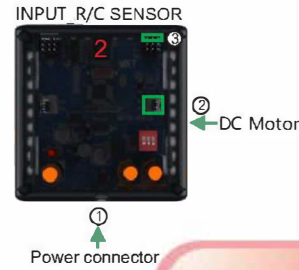
S SIZE

M SIZE

L SIZE

### How to operate Gear left Gear right

#### Connecting the mainboard



- Connect in this order.
1. Connect Battery case to POWER connector.
  2. Connect Right DC motor to RIGHT-Motor connector.
  3. Connect RC receiver to R/C connector.

#### Setting mode

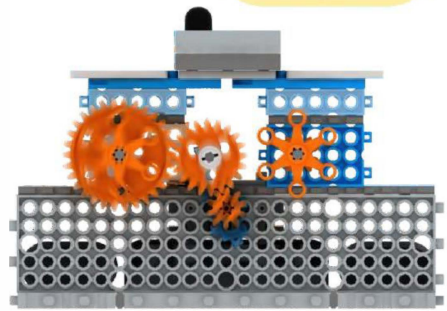
1. Ensure battery case/DC Motor Connector are connected
2. Turn on the power.
3. Press the MODE button and select as the follow mode.



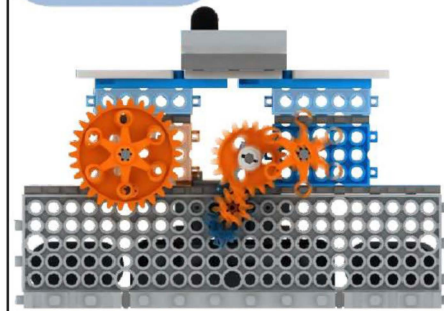
4. Select remote control ID
5. Press the START button.

Press the remote control's left and right button and observe the gears rotation.

#### Motion Pattern



The movement of medium gear will make big gear move slower.



The movement of medium gear will make small gear move faster.